Spinors, Twistors, Quaternions, and the "Spacetime" Torus Topology

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Abstract

The dual torus topology occupies a central role in the spinor, twistor and quaternionic formulation. This topology appears to be ubiquitous in astrophysical and cosmological phenomena and is predicted by the U_4 bubble of the affine connection in the Haramein-Rauscher solution to Einstein's field equations. The geometric structure of the complexified Minkowski space is associated with the twistor algebra, spinor calculus, and the SU_n groups of the quaternionic formalism. Hence quantum theory and relativity are related mathematically through the dual torus topology. Utilizing the spinor approach, electromagnetic and gravitational metrics are mappable to the twistor algebra, which corresponds to the complexified Minkowski space. Quaternion transformations relate to spin and rotation corresponding to the twistor analysis. Keywords: Quaternions, Spinors, Spacetime, Twistors

1. Introduction

In this paper we will present a formalism that uniquely relates electromagnetic and gravitational fields. Through this formalism and the relationship of the spinor calculus and the twistor algebra we can demonstrate the fundamental conditions of such a system which accommodates macroscopic astrophysical phenomena as well as microscopic quantum phenomena.

The generalized hyperdimensional Minkowski manifold has nonlocal as well as anticipatory properties. We have examined elsewhere the topology of the torus $T_1 = U_1 \times U_1$ and the dual torus $T_1 \times T_1$ related to astrophysical systems such as galactic structures, black hole ergospheres, and supernovae phenomenon, etc. Here we discuss the 720° symmetry of the so-termed Dirac string trick within the context of the relativistic form of the Dirac formalism and the relationship to the dual-torus topology. Twistors and spinors are examined and are applicable to the quaternion formalism. The quaternion formalism can be related to the hyperdimensional complexified Minkowski space, Lie groups SU_n , as well as Riemannian topologies and the Dirac equation.

In Section 2., we present the formalism for the role of the spinor calculus which is utilized to relate the expression for the metric tensor to gravitational and electromagnetic field components through the relationship of the twistor algebra and

International Journal of Computing Anticipatory Systems, Volume 22, 2008 Edited by D. M. Dubois, CHAOS, Liège, Belgium, ISSN 1373-5411 ISBN 2-930396-09-1 spinor calculus. The Minkowski space formalism consistent with this approach uniquely relates to the twistors and, as we demonstrate in Section 3., to the dual torus topology. In this section, we demonstrate the manner in which the approaches presented in this paper relate to the current supersymmetry and GUT models as well as string theory. We further elaborate on the symmetry principles of the complexification of Minkowski space, twistors and their properties.

Some unique features of the torus topology and its associated vector space are given in Section 4. A fundamental relationship between the complex Minkowski space, the twistor algebra and quaternions are developed in Section 5. Of interest are the non-Abelian nature of quaternions, the SU_n groups, and quantum theory's relation to tori and other topologies. The basic structures of these spaces demonstrate a set of connections between the dual torus topology and a fundamental structure of "spacetime" leading to the Haramein-Rauscher solution.

2. The Spinor Formalism and Unification, and the Relationship to Twistors and Tori Topology

The approach to unification of the electromagnetic and gravitational fields was developed by Kaluza [1] and Klein [2] in the 1920s and their work was seriously considered by Einstein in the 1930's. This five-dimensional geometry utilizes the spinor calculus to account for the coupling of the electromagnetic field to the gravitational field, in which the spinor is treated as a rolled up dimension rather than as the four extended dimensions of the gravitational field. The concept of small rotational "extra dimensions" is accepted in current ten and eleven dimensional supersymmetry models, and the Kaluza-Klein Theory is treated as a subset of this supersymmetry, including the grand unification theory (GUT).

The Kaluza-Klein Theory requires the periodicity of the five-dimensional spinor fields to unify electromagnetism and gravity based on the homomorphism between the Lorentz group and the unimodular transformation of Maxwell's equations and the weak Weyl limit of the gravitational field. A discussion of the Kaluza-Klein model and the Rauscher [3] and Newman [5] and Hansen and Newmann complex eight-space is given in reference [6]. In the approach of these later three references, the spinor calculus is demonstrated to be mappable one-to-one with the twistor algebra of the complex eight-space and, hence, the Penrose twistor [3].

The coupling of the electromagnetic field with the gravitational field in the Kaluza-Klein may also yield a connection through the photon description of the twistor algebra. The photon is the quanta of the electromagnetic field and the interaction mediation between leptons, of which the electron is one. The five-dimensional spinor calculus has been developed within the five-dimensional relativistic formalism [1, 2, 3]. The spinor calculus developed in the five-dimensional spinor formalism accounts for the coupling of the electromagnetic field to the gravitational metric.

This approach is manifestly five-covariant in a special five-dimensional space. The specific spin frames of reference of the five-dimensional Kaluza-Klein geometry

reduces to the spinor formalism of curved spacetime. The theory of spinors in fourdimensional space is based upon the transformation L' and the group of unimodular transformation U_1 in SL(2, C). Elsewhere we have related this formalism to the toroidal space $U_1 \times U_1$ [7].

Unimodular action of the symplectic automorphism group SL(2,R) of the Heisenberg two step nilpotent Lie group, N has the discrete subgroups SL(2,Z) of SL(2,R). The two-dimensional compact unit sphere $= S_2$ (Riemannian sphere) and the three-dimensional spherical component unit sphere can map as $S_3 \rightarrow R^4$.

It has been established that the five-dimensional 4-component spinor calculus is related to the four-dimensional spinor formalism in order to account for the coupling of the electromagnetic field as a periodic five-dimensional spinor field to the curved space of the gravitational Riemannian metric. We can utilize projection geometry to relate five-dimensional spinor calculus to the four-dimensional twistor space.

An isomorphism between vectors v^{β} and spinors $v^{AA'}$ satisfies the condition

$$\overline{\pi}^{AA'} = \pi^{AA'} \tag{1}$$

so that the spinor equivalent to a vector v^{β} is

$$\tau^{AA'} = \tau^{AA'}_{\beta} v^{\beta} \tag{2}$$

where $\tau_{\beta}^{AA'}$ is a tensor. Therefore,

$$v^{\beta} = \tau^{\beta}_{AA'} \pi^{AA'} \tag{3}$$

where v^{β} is real for $\overline{\pi}^{AA'} = \pi^{AA'}$. The covering map SL(2,C) goes to O(1,3) by using the vector-spinor correspondence.

We present some of the properties and structure of this significant advancement in developing a unified force theory for the electromagnetic and gravitational fields, which we demonstrate are related to the twistor algebra and torus topology [7]. In addition to the general coordinate transformations of the four coordinates x^{μ} , the preferred coordinate system permits the group relation,

$$x'^{5} = x^{5} + f(x^{1}, x^{2}, x^{3}, x^{4}).$$
(4)

Using this condition and the five-dimensional cylindrical metric or $ds^2 = \gamma_{ik} dx^i dx^k$ yields the form

$$ds^{2} = \left(dx^{5} + \gamma_{\mu 5}dx^{\mu}\right)^{2} + g_{\mu\nu}dx^{\mu}dx^{\nu}$$
(5)

where the second term is the usual four-space metric. The quantity $\gamma_{\mu 5}$ in the above equation, transforms like a gauge [10, 11]

$$\gamma'_{\mu 5} = \gamma_{\mu 5} - \frac{\partial f}{\partial x^{\mu}} \tag{6}$$

where the function f is introduced as an arbitrary function. Returning to our fivedimensional metrical form in its five compact form and four- and five-dimensional form gives,

$$\gamma_{\mu\nu} = g_{\mu\nu} + \gamma_{\mu5}\gamma_{\nu5} \,. \tag{7}$$

Proceeding from the metrical form in a "cylindrical" space, $ds^2 = \gamma_{ik} dx^i dx^k$ where indices *i*, *k* run 1 to 5, we introduce the condition of cylindricity which can be described in a coordinate system in which the γ_{ik} are independent of x^5 or

$$\frac{\partial \gamma_{ik}}{\partial x^5} = 0.$$
(8)

Kaluza and Klein assumed $\gamma_{ss} = 1$ or the positive sign $\gamma_{55} > 0$ for the condition of the fifth dimension to ensure that the fifth dimension is metrically space-like. In geometric terms, one can interpret x^5 as an angle variable, so that all values of x^5 differ by an integral multiple of 2π corresponding to the same point of the five-dimensional space, if the values of the x^{μ} are the same. Greek indices μ, ν run from 1 to 4, and Latin indices *i*, *k* run from 1 to 5 and for this specific case, each point of the five-dimensional space passes exactly one geodesic curve which returns to the same point. In this case, there always exists a perpendicular coordinate system in which $\gamma_{55} = 1$ and

$$\frac{\partial \gamma_{5\mu}}{\partial x^5} = 0.$$
⁽⁹⁾

It follows from those properties that $g_{\mu\nu}$ and γ_{ik} can be made analogous so that $g_{\mu\nu} = \gamma_{ik}$ then

$$\gamma^{55} = 1 + \gamma^{\mu\nu}\gamma_{\mu5}\gamma_{\nu5} \tag{10a}$$

(also see equation (7)) and

$$\gamma^{\mu 5} = -g^{\mu \nu} \gamma_{\mu 5}. \tag{10b}$$

The gauge-like form alone is analogous to the gauge group, which suggests the identification of $\gamma_{\mu 5}$ with the electromagnetic potential, ϕ_{μ} . We can write an expression for an antisymmetric tensor,

$$\frac{\partial \gamma_{\mu 5}}{\partial x^{\mu}} - \frac{\partial \gamma_{\mu 5}}{\partial x^{\nu}} = f_{\mu \nu} \tag{11}$$

which is an invariant with respect to the "gauge transformation".

We now use the independence of γ_{ik} of x_5 or $\partial \gamma_{ik} / \partial x^5 = 0$. The geodesics of the metric in five-space can be interpreted by the expression

$$\frac{dx^5}{ds} + \gamma_{\mu 5} \frac{dx^{\nu}}{ds} = C \tag{12}$$

where C is a constant and s is a distance parameter. If we consider the generalized five-dimensional curvature tensor, and using the form for $f_{\mu\nu}$ we can express it in terms of $F_{\mu\nu}$, the electromagnetic field strength,

$$f_{\mu\nu} = \sqrt{\frac{16\pi G}{c^4}} F_{\mu\nu}$$
(13)

where $\sqrt{G/c^4} = \frac{1}{\sqrt{F}}$ where F is the quantized force introduced by Rauscher

[12, 13, 14] which relates to the driving force for the expansion of the universe. Furthermore, this force term F is utilized in the Haramein-Rauscher solution to Einstein's field equations, which incorporates torque and Coriolis effects (see equations (39) to (44) in reference [7]). In work in progress, it appears that the topology of the fluid dynamics of the Haramein-Rauscher solution lead to a dual torus topology. Then we can write,

$$\gamma_{\mu 5} = \sqrt{\frac{16\pi G}{c4}} \phi_{\mu} \,. \tag{14}$$

The integration constant, above, can be identified as proportional to the ratio e/m of charge to mass of a particle traveling geodesics in the Kaluza-Klein space [3].

Under the specific conditions of the conformal mappings in the complex Minkowski space, one can represent twistors in terms of spinors. The spinor is said to "represent" the twistor. The twistor is described as a complex two-plane in the complex Minkowski space (see Section 3 and see reference [3] and references on twistor theory and the spinor calculus cited in this reference). Twistors and spinors can be easily related by the general Lorentz conditions in such a manner as to retain the condition that all signals are luminal in real four-space. The conformal invariance of the tensor field, which can be Hermitian, can be defined in terms of twistors and these fields can be identified with particles [15].

It is through the representation of spinors as twistors in complex Minkowski space that we can relate the complex eight-space model to the Kaluza-Klein geometries and to the grand unification or GUT theory. In the five-dimensional Kaluza-Klein geometries, the extra dimension is considered to be a spatial rotational dimension in terms of $\gamma_{\mu 5}$.

The Hanson-Newman [6], Rauscher [3,4], and the later Haramein-Rauscher [7,8] complex Minkowski space has introduced with it an angular momentum or helix or spiral dimension called a twistor which is expressed in terms of spinors.

The spinor formalism was used by Dirac to define the Schrödinger equation in a relativistic invariant form so that the complex scalar time dependent field of Schrödinger is in terms of a two component spinor field. Using this formalism Dirac obtained a two-valued solution which predicted the observed electron and positron pair. The spinor field or spinor variable, utilized in the Kaluza-Klein geometry, directly relates to the spin degrees of freedom that are observed by the Zeeman effect in atomic spectra. The spin degrees of freedom appear to be fundamental to quantum theory and to relativity and are a good starting point to treat spin in a fundamental manner. The Lorentz four-space representation of relativity can be reduced to the direct product of two two-dimensional complex representations. The spinor variable is the most fundamental representation of a relativistically invariant theory and spin degrees of freedom may be formulated relativistically and, hence, also in a possible "quantum gravity" picture which applies to the Dirac equation. This approach may be applicable to the Penrose twistor.

We have introduced torque and Coriolis forces in Einstein's field equation to form an expression for the spin driving forces that we observe in a vast variety of cosmological, classical, and quantum domain phenomenon [7]. This approach appears to fit well with

the spinor approach in the Dirac formalism in the quantum domain, that is, that the Lorentz conditions applied by Einstein in relativity may be the origin of the spinor and, hence, be the fundamental theory that yields the spinor formalism and the role of spin in physical phenomena [7]. Other implications of the relationship between the Penrose twistor formalism and the complex Minkowski space, which includes anticipatory systems and nonlocality, are given in references [23-27].

3. Penrose Twistor and Harmonic Tori Sequencing and Particle Spin

Interest in the twistor program has been in the form of quantizing gravity in order to unify the physics of the micro- and macro-cosmos in 1971 and 2005. Such a procedure has been taken by Penrose, et al. and is based on the concept of a more general theory that has limits in the quantum theory and the relativistic theory [22,28]. In addition, there have been approaches to the underlying structure of spacetime in the quantum [17] and structural regime [12]. A structured and/or quantized spacetime [12,28] may allow a formalism that unequally relates the electromagnetic fields with the gravitational metric [7-9,13]. Feynman [19,29] and Penrose graphs [17,30] may overcome the divergences of such an approach. In order to translate the equations of motion and Lagrangians from spinors to twistors, one can use the eigenfunctions of the Casimir operators of the Lie algebra of U(2, 2) [30].

For the simplest case of a zero rest mass field (photon-like) for n/2 spin for $n \neq 0$, we can write

$$\nabla_{AA'} \varphi^{A\dots N} = 0 \tag{15}$$

for A,...,N written in terms of N indices, and for N = 1, we have the Dirac equation for massless particles. For a spin zero field, we have the Klein-Gordon equation

$$\nabla^{AA'} \nabla_{AA'} \varphi = 0 \tag{16}$$

and in equation (15) for n = 2, we have the source-free Maxwell equation $\Box F^{\mu\nu} = 0$ for spin 1 or U_1 fields, and for n = 4, we have the spin free Einstein field equations, $R_{\mu\nu} = 0$. The indices μ and ν run 0 to 3. For a system with charge, then $\Box F^{\mu\nu} = J_{\mu\nu} - J_{\nu\mu}$, or this can be written as $\frac{F_{\mu\nu}}{\partial x_{\nu}} = J_{\mu}$ and then we can write

$$\gamma_{\mu\nu} \frac{\partial F_{\mu\nu}}{\partial x_{\nu}} = J_{\mu} . \tag{17}$$

In this section, we outline a program to relate the twistor topology to the spinor space and specifically to the Dirac spinors. Both Fermi-Dirac and Bose-Einstein statistics are considered. The relationship between twistor theory and the Dirac "string trick" model leads a dual torus topology. This topology appears to have, as well, astrophysical consequences such as the Haramein-Rauscher solution to Einstein's field equations and observational data in supernovae dynamics, black hole ergospheres, galactic structures, etc.

The Penrose spin approach is designed to facilitate the calculation of angular

momentum states for SL(2). The spinor formalism, in the Dirac equation, established spinors within quantum theory. The twistor formalisms are related to the structure of spacetime and the relation of the spinors and twistors is also of interest because it identifies a relationship between quantum mechanics and relativity [17, 18, 30, 31].

Twistor theory has been related to conformal field theory and string theory [31]. Also, twistor theory has been related to quaternions and complex quaterionic manifolds [32, 33]. The projective twistor space, PT, corresponds to two copies of the associated complex projective space of CP^3 or $CP^3 \times CP^3$ [31]. It is through the conformal geometry of surfaces in S^4 , utilizing the fact that CP^3 is an S^2 bundle over S^4 , that quaternions can be related to twistors [34].

We can demonstrate a useful relationship between the complex eight-space and the Penrose twistor topology; the twistor is derived from the imaginary part of the spinor field. The Kerr Theorem results naturally from this approach in which twisting is shear free in the limit of asymptotic flat space. The twistor is described as a two-plane in complex Minkowski space, M^4 . Twistors define the conformal invariance of the tensor field, which can be identified with spin or spinless particles. For particles with a specific intrinsic spin, s, we have $Z^{\alpha} \overline{Z}_{\alpha} = 2s$, and for zero spin, such as the photon, $Z^{\alpha} \overline{Z}_{\alpha} = 0$ where \overline{Z}_{α} is the Hermitian conjugate of Z^{α} , and Z^{α} and Z_{α} can be regarded as canonical variables such as \underline{x} , \underline{p} in the quantum theory phase space analysis. The twist free conditions, $Z^{\alpha} \overline{Z}_{\alpha}$, hold precisely when Z^{α} is a null twistor. The upper case Latin indices are used for spinors, and the Greek indices for twistors. The spinor field of a twistor is conformally invariant and independent of the choice of origin [35]. For the spinor, the indexes A and A' take on values 1, 2 (see references [17, 18]). We briefly follow along the lines of Hanson and Newman in the formalism relating the complex

Twistors and spinors are related by the general Lorentz conditions in such a manner as to retain the fact that all signals are luminal in the real four-space, which does not preclude superluminal signals in an N > 4 dimensional space. The twistor Z^{α} can be expressed in terms of a pair of spinors, ω^{A} and π_{A} , which are said to represent the twistor. We write

$$Z^{\alpha} = \left(\omega^{A}, \pi_{A'}\right) \tag{18}$$

where $\omega^{A} = i r^{AA'} \pi_{A'}$

Minkowski space to the twistor algebra [6].

Every twistor Z^{α} is associated with a point in complex Minkowski space, which yields an associated spinor, ω^{A} , $\pi_{A'}$. The spinor is associated with a tensor which can be Hermitian or not. The spinor can be written equivalently as a bivector forming antisymmetry. In terms of spinors ω^{A} and $\pi_{A'}$, they are said to represent the twistor Z^{α} as $Z^{\alpha} = (\omega^{A}, \pi_{A'})$ (see equation (18)). In terms of components of the twistor space in Hermitian form, φ for $\varphi_{AA'} = \varphi_{A'A}$, we have,

$$\varphi\left(\mathbf{Z}^{\alpha}\mathbf{Z}^{\beta}\right) = \overline{\mathbf{Z}^{0}\mathbf{Z}^{2}} + \overline{\mathbf{Z}^{1}\mathbf{Z}^{3}} + \overline{\mathbf{Z}^{2}\mathbf{Z}^{0}} + \overline{\mathbf{Z}^{3}\mathbf{Z}^{1}}$$
(19)

where the α index runs 0 to 3. The components of Z^{α} are $Z^{0}, Z^{1}, Z^{2}, Z^{3}$ and are identifiable with a pair of spinors, ω^{A} and $\pi_{A'}$, so that

$$\omega' = Z^1, \ \pi_{0'} = Z^2, \ \pi_{1'} = Z^3 \tag{20}$$

so that we have

$$Z\overline{Z}_{\mu} = \mu^{0}\overline{\pi}_{0} + \mu'\overline{\pi}_{1} + \pi_{0}'\overline{\mu}' + \pi_{1'}\overline{\mu}'.$$
 (21)

Note that the spinor ω^A is the more general case of μ^A . This approach ensures that the transformations on the spin space preserve the linear transformations on twistor space, which preserves the Hermitian form, φ .

The underlying concept of twistor theory is that of conformal invariance or the invariance of certain fields under different scalings of the metric $g_{\mu\nu}$. Related to the Kerr theorem, for asymptotic shear-free null flat space, the analytic functions in the complex space of twistors may be considered a twisting of shear-free geodesics. In certain specific cases, shear inclusive geodesics can be accommodated. We consider the shear modulus W and a spacetime torque term $\tau_{\mu\nu}$ as the source of the shear inclusive geodesics in the stress energy tensor of Einstein's field equation in reference [7].

Twistors are formally connected to the topology of certain surfaces in complex Minkowski space M^4 . This space, the complex space C^4 , is the cover space of R^4 , the four dimensional Riemannian space. On the Riemann surface, one can interpret spinors as roots of the conformal tangent plane of a Riemann surface into R^3 . This approach is significant because it ensures the diffeomorphism of the manifold. Complexification is formulated as $Z^{\mu} = X_{Re}^{\mu} + X_{Im}^{\mu}$, which constitutes the complexification of the Minkowski space, M^4 . The usual form Minkowski space is a submanifold of complex Minkowski space. Twistors are spacetime structures in Minkowski space, which is based upon the representation of twistors in terms of a pair of spinors as we have shown [4, 21]. Twistors provide a unique formulation of complexification. The interpretation of twistors in terms of asymptotic continuation accommodate curved spacetime. One feature of this approach to quantum theory in twistor space leads to a quantum gravity theory [21].

This spinor representation of a twistor makes it possible to interpret a twistor as a two-plane in complex Minkowski space, M^4 . Then we can relate ω^A and $\pi_{B'}$ so that $\xi^{AA'}$ is a solution as

$$\omega^{A} = i\xi^{AB'}\pi_{B'} \tag{22}$$

for the position vector $\xi^{AB'}$ in the complex Minkowski space. We can also consider the relationship of $Z^{AA'}$ and $\pi^{A'}$ to a complex position vector as

$$\mathbf{Z}^{AA'} = \boldsymbol{\xi}^{AA'} + \boldsymbol{\omega}^A \boldsymbol{\pi}^{A'} \tag{23}$$

where ω^A is a variable spinor. Just as in the conformal group on Minkowski space, spin space forms a two-valued representation of the Lorentz group. Note that SU_2 is the four

value covering group of C(1, 2), the conformal group of Minkowski space. The element of a four dimensional space can be carried over to the complex eight-space.

For spin, *n* the Dirac spinor space is a covering group of SO_n where this cohomology theory will allow us to admit spin structure and can be related to the SU_2 Lie group. Now let us consider the spin conditions associated with the Dirac equation and further formulate the manner in which the Dirac "string trick" relates to the electron path on the double torus topology.

For a spin, $s = \frac{1}{2}$ particle, the spin vector u(p) is written as $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$ and $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$ for spin up

and spin down and p is momentum. For a particle with mass we have for $c \neq 1$,

$$\left(-i\hbar c\,\alpha_{\mu}\frac{\partial}{\partial x_{\mu}}+\beta mc^{2}\right)\psi=0$$
(24)

for the time independent equation, and we can divide Eq. (24) by $i\hbar c$ and have,

$$\left(\gamma_{\mu}\frac{\partial}{\partial x_{\mu}} + \frac{mc}{\hbar}\right)\psi = 0$$
(25)

where $k_{\circ} = mc/\hbar$ and $\gamma_{\mu} = i\hbar c \alpha_{\mu}$ where indices μ run 0 to 3. The dependent Dirac equation is given as,

$$\left(-i\hbar c\,\alpha_{\mu}\frac{\partial}{\partial x_{\mu}}+\beta mc^{2}\right)\psi+\frac{i}{\hbar}\frac{\partial\psi}{\partial t}=0\,.$$
(26)

The solution to the Dirac equation is in terms of spin u(p) as

$$\psi = u(p)e\frac{i}{\hbar}(p \cdot \underline{x} - Et)$$
⁽²⁷⁾

the Dirac spin matrices $\gamma_{\mu} = i\hbar c \alpha_{\mu}$. The spinor calculus is related to the twistor algebra, which relates a two-space to an associated complex eight-space (see references [37, 38]).

An example of the usefulness of spinors is in the Dirac equation. For example, we have the Dirac spin matrices, $\gamma_{\mu} = \begin{pmatrix} 0 & \sigma_{\mu} \\ \sigma_{\mu} & 0 \end{pmatrix} = -i \beta \alpha_{\kappa}$ where terms such as $\gamma_{\mu} (1 - \gamma_5)$ come into the electroweak vector-axial vector formalism. The three Dirac spinors (also

called Pauli spin matrices) are given as

$$\sigma_{x} = \begin{vmatrix} 0 & 1 \\ 1 & 0 \end{vmatrix}, \sigma_{y} = \begin{vmatrix} 0 & -i \\ i & 0 \end{vmatrix} \quad \text{and} \quad \sigma_{z} = \begin{vmatrix} 1 & 0 \\ 0 & -1 \end{vmatrix}$$
(28)

and $\gamma_5 \equiv i\gamma_0\gamma_1\gamma_2\gamma_3 = i\gamma^0\gamma^1\gamma^2\gamma^3$ for $\gamma_0 = \beta$ is given as,

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$$\nu_0 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$
(29)

for trace $tr\beta = 0$, that is, Eq. (29) can be written as,

$$\gamma_0 = \beta = \begin{pmatrix} I_2 & 0\\ 0 & -I_2 \end{pmatrix}$$
(30)

where we have the 2×2 spin matrix as $I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$. Note that the Dirac spinors are the

standard generators of the Lie algebra of SU_2 .

The commutation relations of the Dirac spin matrices is given as

$$\left\{\gamma^{\mu},\gamma^{\nu}\right\}_{+}=\gamma^{\mu}\gamma^{\nu}+\gamma^{\mu}\gamma^{\nu}=ig^{\mu\nu}I_{\sim}$$
(31)

and det $|\gamma_{\mu\nu} = \det ||g_{\mu\nu}||$ where $g_{\mu\nu}$ is the metric tensor. The Dirac spin matrices come into use in the electroweak vector-axial vector model as $\gamma_{\mu}(1-\gamma_5)$ for γ_5 as,

$$\gamma_5 = i \gamma_0 \gamma_1 \gamma_2 \gamma_3 = i \gamma^0 \gamma^1 \gamma^2 \gamma^3 \tag{32}$$

where indices run 0 to 3.

We can also write,

$$\gamma_{\mu\nu}(x^{5}, x^{\mu}) = \sum_{n=-\infty}^{\infty} \gamma_{\mu\nu}^{(n)}(x^{\nu}) e^{inx^{5}}$$
(33)

which expresses some of the properties of a five-dimensional space having $\gamma_0, \gamma_1, \gamma_2, \gamma_3$ and γ_5 . Note that γ_5 is associated with a five-dimensional metric tensor. This fivedimensional space passes exactly one geodesic curve which returns to the same point with a continuous direction. Note that this is a similar formalism to that of the Dirac string trick 720° path which can be mapped to the surface of a double torus.

A connection can also be made to the electromagnetic potential; and the metric of the Kaluza-Klein geometry. We can express γ_{u5} in terms of a potential φ_{u} so that

$$\gamma_{\mu 5} = \sqrt{2\kappa}\phi_{\mu} \tag{34}$$

where $\kappa \equiv \frac{8\pi}{F}$ and where $F = \frac{c^4}{G}$ or the quantized cosmological force [7,12,13] (also see equation (14)). Then we have a five-space vector as,

$$\gamma_{\nu 5} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}.$$
 (35)

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Through this approach, we can relate covariance and gauge invariance [21].

Using Poisson's equation,

$$\nabla \varphi_{\mu} = \frac{1}{2} \kappa c^{4} \mu_{0} \tag{36}$$

where again $\kappa \equiv \frac{8\pi}{F}$ as above. The electromagnetic field, $F_{\mu\nu}$, can be expressed as,

$$F_{\mu\nu} = \frac{\partial \varphi_{\mu}}{\partial x^{\nu}} - \frac{\partial \varphi_{\nu}}{\partial x^{\mu}}$$
(37)

which yields an interesting relation of the gravitational metric to the electromagnetic field. Also the Lagrangian is given as $L = \frac{1}{2}F^{\mu\nu}F_{\mu\nu}$ so that $L = L\sqrt{-g}$ for the metric

g. Note $L = \int \sqrt{g} d\tau$, where $d\tau$ represents a four space. Now let us return to our discussion of the twistor algebra and relate it to the spinor calculus. The Penrose twistor space also yields a five-dimensional formalism as is also formulated by the Kaluza-Klein theory.

Both projective and non-projective twistors are considered as images in a complex Riemannian manifold in its strong conformal field condition. Duality, analytic continuation, unitary and other symmetry principles can be incorporated by using appropriate (Bose-Einstein or Fermi-Dirac) spin statistics in analogy to the Hartree-Fock spaces or Fock space. Particles can be considered as states as the Fock space elements or the "end" of each disconnected portion of the boundary of the manifold.

The quanta are associated with a quantum field of particles that carry both momentum and energy. The total energy Hamiltonian can be defined in terms of a number of simple phonon states which can be expressed in terms of a_n^+ creation and a_n destruction operator states. Since all creation operators commute, these states are completely symmetric and satisfy Bose-Einstein statistics. Such phonon states, having a definite number of phonons, are called Fock states, which is the vector sum of the momentum of each of the photons in the state. The ground state $|0\rangle$ can be considered the photon vacuum state or Fock state where the photon is taken as a phonon state. The creation and destruction operators commute as $\{a_n, a_n^+\} = \delta_{nn'}$ for the delta function $\delta_{nn'}$ [39].

In this picture, we can consider an *n*-function as a "twistor wave" function for a state of *n*-particles. Penrose [17] considers a set of *n*-massless particles as a first order approximation. We form a series on a complex manifold as elements of the space C_n as

$$f_0, f_1(z^{\alpha}), f_2(z^{\alpha}, y^{\alpha}), f_3(z^{\alpha}, y^{\alpha}, x^{\alpha}), \dots$$
 (38)

which are, respectively, the 0th function, 1st function, 2nd function, and 3rd function, etc. of the twistor space, which are also elements of C_n . We can also consider f_0 , f_1 , f_2 , f_3 , as the functions of several nested twistors in which f_0 is the central term of the wave of the twistor space. We can say that these nested tori can act as a recursive sequence. In work in progress we consider a recursive fractal function of nested tori, that may be best expressed in fractal quaternions [15], to define the magnetohydrodynamic structure of spacetime at all scales (see reference [8] for related work).

Penrose [17, 18] suggests that, to a first approximation, f_1 corresponds to the amplitude of a massless, spin 1 particle, f_2 to a lepton spin $\frac{1}{2}$ particle, and f_3 to Hadron particle states, and f_4 to higher energy and exotic Hadron particle states. Mass results from the breaking of conformal invariances for f_n for n = 2 or greater, similar to the S-metric approach [40]. The harmonic functions f_n form a harmonic sequence, where f_n for n = 2 form the Fermion states, and f_n for n = 3 form the Hadron twistor states. Essentially, in the twistor space, we have a center state f_0 around which f_1 , f_2 , ... occur. Each of these sequences of waves forms a torus, hence, f_1 and f_2 form a double nested tori set consistent with both spin 1 and spin $\frac{1}{2}$ particle states where all n states are elements of the twistor, z, as $n \in z$.

In the specific case of a massless particle with spin for f_1 , the two-surface in complex Minkowski space corresponding to the twistor represents the center of mass of the system so that the surface does not intersect the real Minkowski space. This reflects the system's intrinsic spin. We see an analogy to the triple tori Calabi-Yau string theory [41]. The higher order f_n may describe higher order string modes or oscillations of $Z^{\alpha}\overline{Z}_{\alpha} = 0$ or f_0 . This occurs for the case using f_1 , f_2 , and f_3 and, hence, all known particle states.

We can consider the topology of three Penrose projective twistor states which are PT, PT^+ , and PT^- . The PT^+ , and PT^- are meant to represent the domain of PT where we denote these two states in which (-1,1) are elements of t where ε is small. We denote two line elements which are denoted in terms of twistors as a surface on the sphere S^3 as PT^{\pm} which corresponds to $Z_{-t}^{\alpha} \overline{Z_{\alpha}} = 0$ and $Z_{t}^{\alpha} \overline{Z_{\alpha}} = 0$ for $t = 1 - \varepsilon$ for PT^+ , and PT^- gives $t = 1 - \varepsilon = \varepsilon - 1$. These two branches correspond to a transformation matrix,

| (1 | 0 | t | 0) | | | |
|--|---|---|----|---|------|--|
| $ \begin{pmatrix} 1 \\ 0 \\ t \\ 0 \end{pmatrix} $ | 1 | 0 | t | | (20) | |
| t | 0 | 1 | 0 | • | (39) | |
| (0 | t | 0 | 1) | | | |

This gives us a translation formulation for vectors into the states of spinors in terms of t, in terms of the spinors

$$\begin{pmatrix} \omega^{0} \\ r_{1} \\ \omega^{1} \\ r_{\prime} \\ r_{\prime} \\ r_{\prime} \\ r_{\prime} \\ r_{\prime} \\ r_{\prime} \end{pmatrix} = \begin{pmatrix} 1 & 0 & t & 0 \\ 0 & 1 & 0 & t \\ t & 0 & 1 & 0 \\ 0 & t & 0 & 1 \end{pmatrix} \begin{pmatrix} \omega_{1}^{0} \\ \omega^{1} \\ \pi_{0} \\ \pi_{1} \end{pmatrix}$$
(40)

which is Z_t^{α} and $t \sim \pm 1$ since ε is small. Then in terms of twistors,

$$\hat{\omega}^{A} = \omega^{A} + \varepsilon \xi^{AB} \frac{\partial f}{\partial \omega^{B}}$$
(41)

for $\hat{\pi}_{A'} = \pi_{A'}$ where ω and π are orthogonal spinors. The term $\varepsilon \xi^{AB} \frac{\partial f}{\partial \omega^B}$ is small compared to ω^A and π_A since ε is small. The unit spinors or vectors are $\hat{\omega}^A$ and $\hat{\pi}_{A'}$ for both A, B = 1, 2.

The projective twistor space, PT, corresponds to two copies of CP^3 , which has an associated complex projective space. The PT space is the space which yields the torus topology of the Riemann surface of genus g = 1. The genus 1 topology contains one "hole" or singularity, genus 2, two holes, etc. The two-hole system is a continuous manifold which can represent two connected tori or a double torus producing an equatorial planar membrane. This topology is related to the high-energy plasma dynamics found around black hole ergospheres and their equatorial accretion disks. It is, as well, observed in stars, and gas and dust circulation within galactic disks and halos. Observation of double tori topology at the cosmological level may, as well, be evidence of a structured polarized vacuum interacting with the high energy plasma dynamics at these scales [8].

4. Some Considerations of the Uniqueness of Vector Space and Torus Topologies

We explore some unique features of the torus topology and their possible vector spaces. We consider the relationship between the $T = U_1 \times U_1$ group and the S^2 group. An example of the n- dimensional manifold, which is not a product of n-onedimensional manifolds, is given by the sphere S^n . When one deals with two or more real or complex variables, there is usually a manifold, M, on which these functions are definable. We explore some of the unique surface features of the torus topology and compare them to the Euclidian spherical topology. The surface of a sphere of unit radius in three-dimensional Euclidian space, S^2 , can be triangulated on the boundary of a tetrahedron. For the torus, T, its triangulation, K, consists of seven 0-simplexes and fourteen 2-simplexes. The contractable one-dimensional sub-polyhedron of K contains all vertices of K. The two generators commute so that the torus group is generated by the two commuting generators $\simeq Z \oplus Z$ (see Section 5). The manifold T^n is the *n*-dimensional torus. If n = 2, then $T^2 = S^1 \times S^1$ defines a torus. The torus is a subset of R^3 , where *R* is the topology on the real numbers. The sets *X* and *Y* are called the topological space. If *X* is a set as a discrete topology, then *Y* can be a collection of all subsets of *X*, i.e., the set 2^x . Any finite or infinite subcollection $\{Z_{\alpha}\}$ of the X_{α} has the property that $\bigcup Z_{\alpha i} \in Y$, or the union of $Z_{\alpha i}$ are elements of *Y*. The torus is a subset of R^3 , and $T^2 = S^1 \times S^1$ is the Cartesian product of two subsets of R^2 so that it is at least a subset of $R^2 \times R^2 = R^4$. The torus, which is in R^3 , is not flat, but the torus $S^1 \times S^1$ in R^4 can be considered flat. Interestingly, the topology of the two tori are the same, which has to do with the precise definition of flatness and curvature.

The definition of curvature depends on the specification of a Riemannian metric [42]. Once we specify the Riemannian metric as we have done in reference [7], then we can define our flatness of T^2 . This entails the specification of the metric $g_{\mu\nu}$ or $\eta_{\mu\nu}$ which allows us to specify the restrictions that the points in R^3 lie on the torus. Then, with respect to the metric $\eta_{\mu\nu}$ (which is the distortion of the metrical space resulting from our torque term $\tau_{\mu\nu}$ in the stress energy tensor of the field equations), we have a curved space torus. For $T^2 = S^1 \times S^1$, which defines two points (x, y) and (x', y') in T^2 , the difference is expressed as $\left[(x - x')^2 + (y - y')^2 \right]^{\frac{1}{2}}$ for the usual $g_{\mu\nu}$. For this metric T^2 is flat and does not lie on R^3 . The reason for this condition is that for a two-dimensional, compact, connected surface to lie in R^3 , it must have at least one non-zero curvature.

In defining a vector space on a sphere S^2 , or torus T, we consider a simple observation of a two dimensional surface in R^3 . For example, a disk $x^2 + y^2 \le a^2$ for z = 0 has a top side and a bottom side, or a sphere S^2 has an inside and an outside, as does the torus T^2 . These two-sided surfaces are defined as orientable since we can use their two-sided properties to define directions or orientations of vectors projected from their surfaces in R^3 . Hence, we have two normals at each point, an inward, or outward pointing normal vector \hat{n} .

If we consider outward normal vectors only, i.e., one-sided or top-sided vector arrays at each point, then for short vectors, in analogy to a "crew cut" in a Euclidian space, no division or part will occur in S^2 space. However, in a curvilinear vector space where the normal vectors are long and curved on a S^2 spherical space, a non-uniformity or "part" will occur in this vector space of an S^2 space. In the case of top-sided vectors, normal to a torus, both short and long vectors will not have a "part" or discontinuity in vector curvature because the "hairs" can be "combed" along the tori space continuously. These normals can be curved in this topological space. It is clear that all non-normal vectors to a sphere, either short or long, will have a "part", but those which lie on the surface of a torus will not require a "part" but may be more densely packed at the curved surface of the inner ring of the torus as compared to the outer ring of the torus. That is, the vector density is greater in the inner surface of the "hole" genus g = 1 than in the outer region of the torus topology; clearly, particle density can change. Hence, we are guaranteed, in general, a diffeomorphic manifold for a torus in curved space, but not in general, for a spherical topology. Therefore, for any non-Euclidian space, diffeomorphism holds for the torus topology.

5. Quaternions, Groups, and Allowable Spatial Structures

The complexified rotational dimensionality of quaternions may be the most appropriate approach to the description of twistor space in the context of a fundamental rotational force embedded in the structure of spacetime itself – spacetime torque [7]. We explore some of their interesting and related properties in this section.

5.1 Quaternion Formalism and Simple Topological Spaces

The quaternion group is isomorphic to the group with elements 1, -1, -i, j, k, -k, and $i^2 = j^2 = k^2 = -1$ and ij = k, jk = i, ki = j. These properties operate similar to complex numbers where $i = \sqrt{-1}$ and i = -1. In the case of the quaternions, i, j, k can represent orthogonal dimensions in three-space. The isomorphism condition states that the group elements of two groups can have a one-to-one correspondence, which is preserved under combinations of elements. Then one can construct a group table as a square array; this is only necessary for higher order groups. Quaternion groups have SU_2 or SU_3 subgroups and can be related to $O_3 + .$

Symmetric groups such as the quaternion group, which is a two-dimensional unimodular unitary group, are simply reducible groups. Following Hamilton, we identify Euclidian four-space with the space of quaternions so that $H = \{\rho + xi + yi + zk\}$ where $\rho, x_o, y, z \in \mathbb{R}^4$ are elements of the Riemannian space \mathbb{R}^4 . The Euclidian three-space is the subset of imaginary quaternion, $H_{im} = \{xi + yi + zk\}$ where $x, y, z \in \mathbb{R}^3$ (see Section 3).

5.2 Quaternions and Quantum Theory

The key is that the Dirac string trick represents the properties of the symmetric group which is SU_2 . The SU_2 is isomorphic with the unit length of the quaternion in fourdimensional space. Quaternions, constructed by Hamilton, can represent rotations in three-space, which can be performed without matrices. They also obey non-Abelian algebra. Furthermore, correspondence of quaternions can be made to vectors and tensors. Quaternions are a viable algebra for understanding rotations in three- and fourdimensional space. Due to symmetry considerations in the Dirac electron theory, a 720° twist is required for the electron to return to the exact same quaternion state, where a 360° rotation will not and must be doubled. Quaternions are a complex number system with properties similar to the Rauscher [4] and Newman [5] complex eight-space. In the usual notation, we start from any complex number, a + ib where a and b are real, where $a \times 1 = a$ and ib is imaginary. The quaternion is written as t + ia + jb + kc where t, a, b, and c are real and they are multiples of a real unit 1 and imaginary units i, j, and k. The following conditions,

$$jk = -kj = i \tag{42a}$$

$$ki = -ik = j \tag{42b}$$

$$ij = -ji = k \tag{42c}$$

and

$$i^2 = j^2 = k^2 = -1 \tag{42d}$$

and

 $ijk = -1 \tag{42e}$

also

$$i^2 = j^2 = k^2 = ijk = -1 \tag{42f}$$

which yields a set of recursive relationships.

Quaternions also have multiplicative properties similar to the complex Minkowski eight-space. Let w = t + ia + jb + kc, then the conjugate of w is \overline{w} and is given as $\overline{w} = t - ia - jb - kc$, and the modulus is given as, $w\overline{w}$ or,

$$ww = t^2 + a^2 + b^2 + c^2.$$
(43)

In fact, quaternions contain all the properties of complex numbers except for commutivity and thus comprise a non-Abelian algebra such as in the quantum theory. Note that we have used a slightly different notation from Hamilton; that is, we write ia, jb, etc., instead of ai, bj, etc. Quaternions are comprehensively explored by L.H. Kauffman. (see references [15, 43]).

If t = 0, then we have a pure imaginary quaternion or

 $u = ia + jb + kc \tag{44a}$

and then

$$u^2 = -(a^2 + b^2 + c^2)$$
(44b)

and are of a unit length

$$a^2 + b^2 + c^2 = 1 \tag{45}$$

so that $u^2 = -1$. Also for two pure imaginary quaternions

$$uv = -u \cdot v + u \times v \tag{46}$$

as the dot and cross product of vector-like quantities in three-space. The addition of the scalar component connotes a coordinate in the fourth dimension and hence we see the analogy of quaternions to the four-dimensional Minkowski space, where t is time, and a corresponds to x, b to y, and c to z. What is unique then about the quaternionic "space" is that we have, for example, the permutation relations from equations (42a) to (42f), and thus quaternions form a non-Euclidian set with the properties for pure quaternions uv in equation (46). We can form a set of pure quaternions on a two dimensional sphere of -1 in each of the three quaternion directions i, j, k. Note that the

complex Minkowski space is formed by one imaginary component i, multiplied by x, y, and z. Now consider A and B real numbers and u is a unit length of a pure quaternion, then $u^2 = -1$ and the powers of A + Bu occupy the same form as powers of complex numbers. That is, u is indistinguishable from any other $\sqrt{-1} = i$.

Let us now relate the quaternions to a complex number Z = A + uB which we can write as $Z = \cos \theta + R \sin \theta$ or, in general,

$$Z^{n} = R^{n} \cos(n\theta) + R^{n} \sin(n\theta)u.$$
(47)

We can proceed with mapping of the n^{th} roots of the quaternions. Consider a space of N+1 dimensions in which we represent N+1 space in the form of A+Bu, where A is a scalar and B is a real number. Now u is a limit vector in an N – space represented as R^N which is a Euclidian N – space. The vector-like quantity u belongs to the unit sphere S^{N-1} about the origin R^N and is taken to have squares equal to minus one, or $u^2 = -1$ for all vectors S^{N-1} . In general, uv is not defined in a higher dimensional geometry such as the eight-dimensional Minkowski space of Rauscher [4] and Newman [5]. We can, however, create power maps of the form $Z^n + K$ where K is a vector in R^{N+1} and Z = A + Bu for $u^2 = -1$ for all u in S^{N-1} . With this approach, we can form classes of hypercomplex iterative processes with incursion in any arbitrary dimensional space. This is the key to Kauffman's ability to relate the hypercomplex interactions formed from quaternions to define higher dimensional fractal sets [43]. In particular, he utilizes this method to explore higher dimensional Mandelbrot and Julia sets. We have explored the use of fractals in describing physical phenomena [44].

One of the basic principles of the quaternion twist holds for the Dirac string trick for 720° degree rotation. A half cycle of twist, or 360 degrees, is expressed in terms of quaternions as ijk = -1. To return to +1, another twist through 360° must occur. Spin must involve a preferred geometry in space [43]. The geometry of a preferred direction can be constructed by the magnitude of total electron transfer. The Penrose spin approach is utilized to calculate angular momentum and SL(2).

In terms of complex analysis involving quaternions, a single 180 degree turn is an instance of $i = \sqrt{-1}$ where $i^2 = -1$ and represents a 360 degree right- or left-handed turn. The case for $i^3 = -i$ is a non-trivial rotation and $i^4 = 1$ returns the rotation of the electron and observer to their original states, through the 720 degree rotation – hence, the interpretation of the quaternionic formalism of one square root of -1 for every direction in three-dimensional space.

We can consider the movement of the electron on the bounded space of a double torus stacked in such a way to have contiguous surfaces at the equatorial plane [7]. In order for the electron to pass through a 720 degree rotation and return the spin and chirality to its original state, the electron path must be different than that of a sphere. A double torus is a likely topology and may result from a fundamental torquing force and Coriolis effect on the spacetime manifold of a polarized vacuum.

In quantum theory, the symmetry group is the SU_2 group rather than the threedimensional space rotation group such as O_3^+ . The SU_2 group is isomorphic with the quaternions of unit length in four-dimensional space. In references [44, 45], the group theoretic approach that relates spinors, twistors, and quaternions is detailed. A spinor is a vector in two complex variables. Antisymmetric conditions lead to the second twist involving the quaternions to create the cycle of the electron to its original state. The antisymmetric conditions utilizing spin calculations can be conducted with Clebsch-Gordan coefficients, 3j and 6j symbols and other components of angular momentum [46]. Through these means, one can calculate the correct spin interactions involving multi-particle quaternion states. We will not pursue this further here but it is a work in progress [44]. Suffice it to say that the iterative properties, formulated here, have a variety of applications such as scalable inclusive relations from the quantum domain to astrophysical and cosmological systems [28].

6. Conclusion

We have demonstrated a unique relationship of the dual torus topology to the spinor calculus, twistor algebra and the quaternionic formalism. This topology appears to be ubiquitous in Nature and may result from spacetime torque and Coriolis forces generating spin/rotation at all scales, from galactic and stellar objects, supernovae, to the weather patterns in the Earth's atmosphere, and may even be a key to defining an electron's path. The tori form appears to also occupy a role in unification models through the E_8 group utilized in supersymmetry models.

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